Computational Physics Lecture-20 M. Reza Mozaffari Physics Group, University of Qom

Contents

- Basis Concepts
- Numerical Differentiation
- Numerical Integration
- Numerical Finding Root
- Classical Scattering
- Solving Linear Systems
- Transmission of Rectangular Barriers
- Approximation of a Function

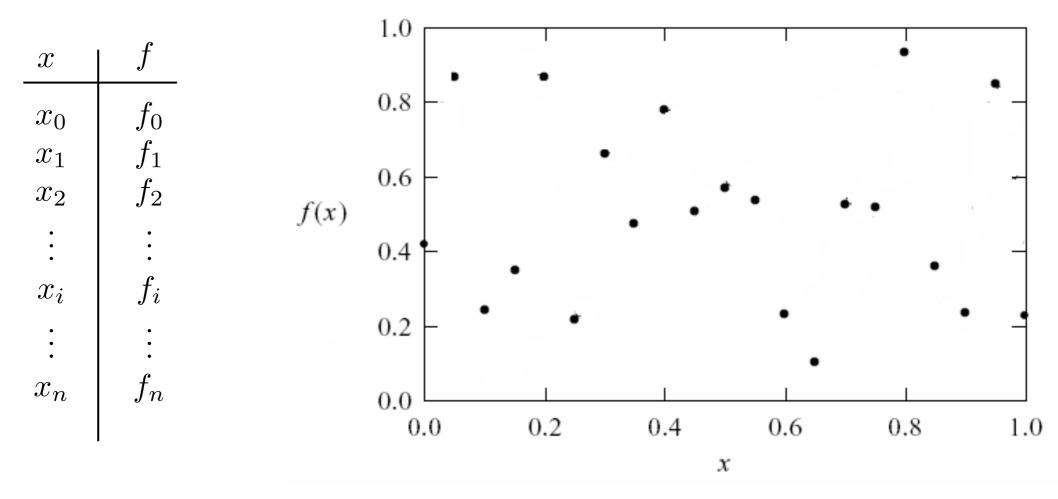
Interpolation is needed when we want to infer some **local information** from a set of incomplete or discrete data.

- Lagrange Interpolation
- Spline Approximation

Overall approximation or fitting is needed when we want to know the **general or global behavior** of the data.

• Least Square

• Lagrange Interpolation



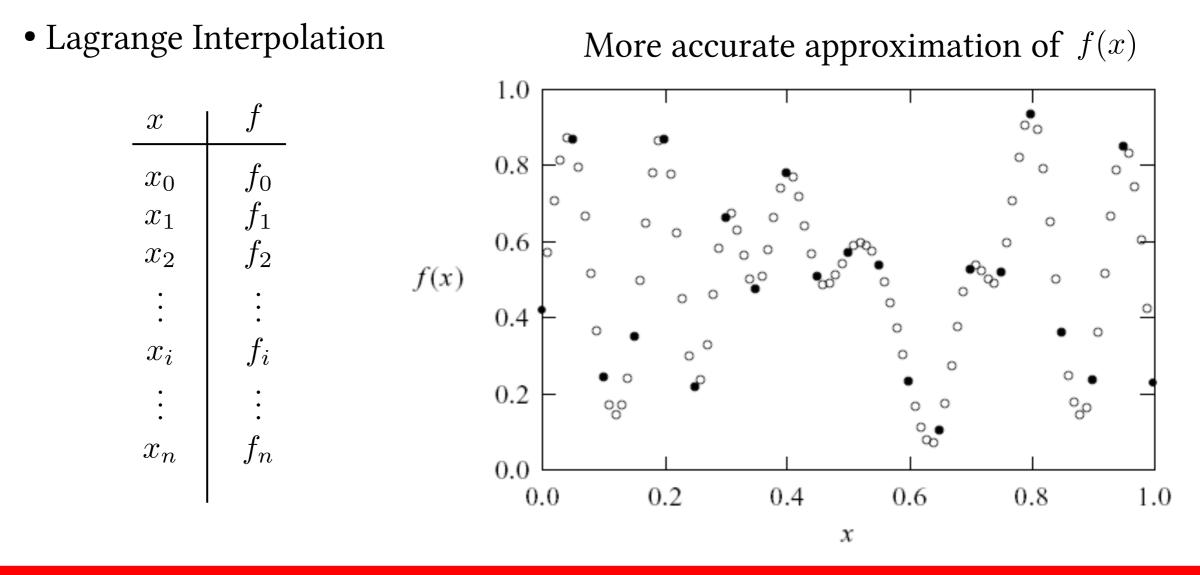
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• Lagrange Interpolation Simplest way to obtain the approximation of f(x)1.0f \mathcal{X} 0.8 f_0 x_0 f_1 x_1 0.6 f_2 x_2 f(x)٠ 0.4٠ f_i x_i 0.2 • f_n x_n 0.00.00.2 0.4 0.6 0.81.0х

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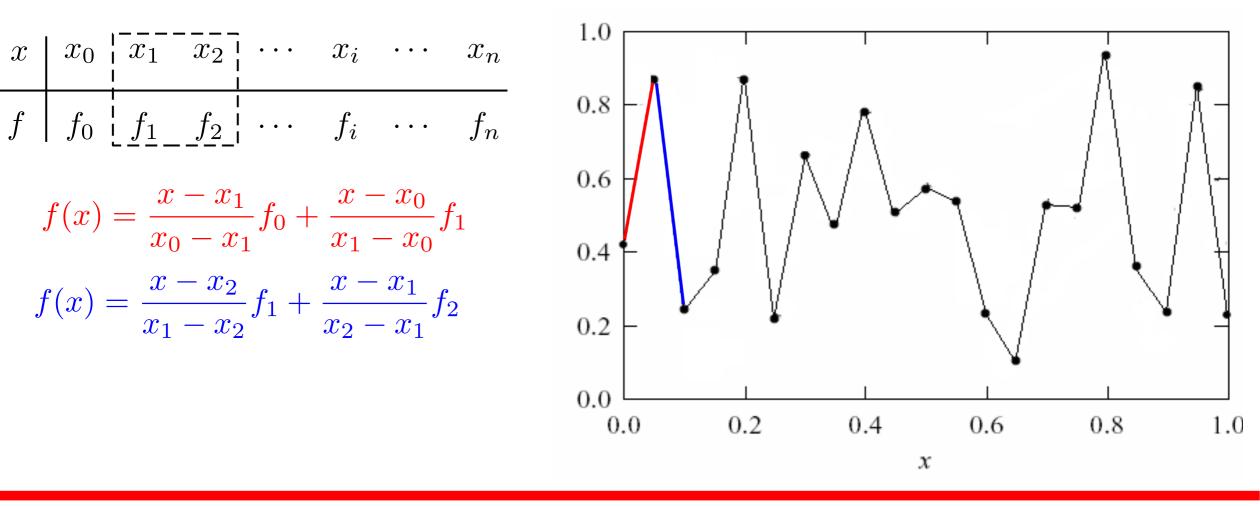
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• Lagrange Interpolation Simplest way to obtain the approximation of f(x)1.0 $x_1 \mid x_2 \quad \cdots \quad x_i \quad \cdots \quad x_n$ x_0 \mathcal{X} 0.8 $f_0 \quad f_1 \mid f_2 \quad \cdots \quad f_i \quad \cdots \quad f_n$ f 0.6 $f(x) = \frac{x - x_1}{x_0 - x_1} f_0 + \frac{x - x_0}{x_1 - x_0} f_1$ 0.4 0.2 0.00.00.2 0.40.6 0.81.0х

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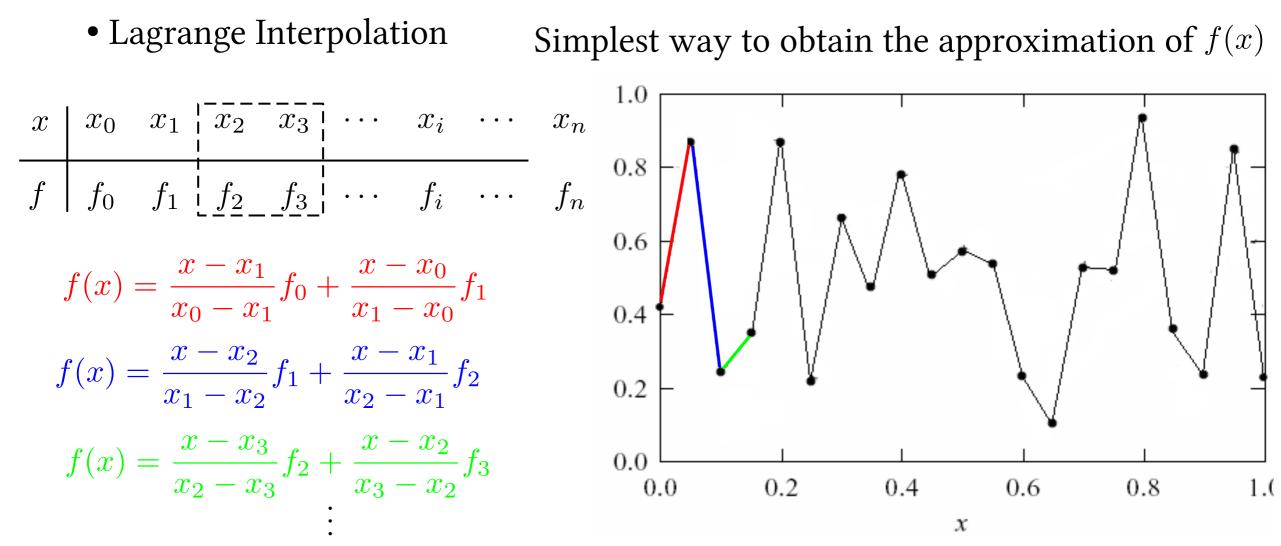
• Lagrange Interpolation

Simplest way to obtain the approximation of f(x)



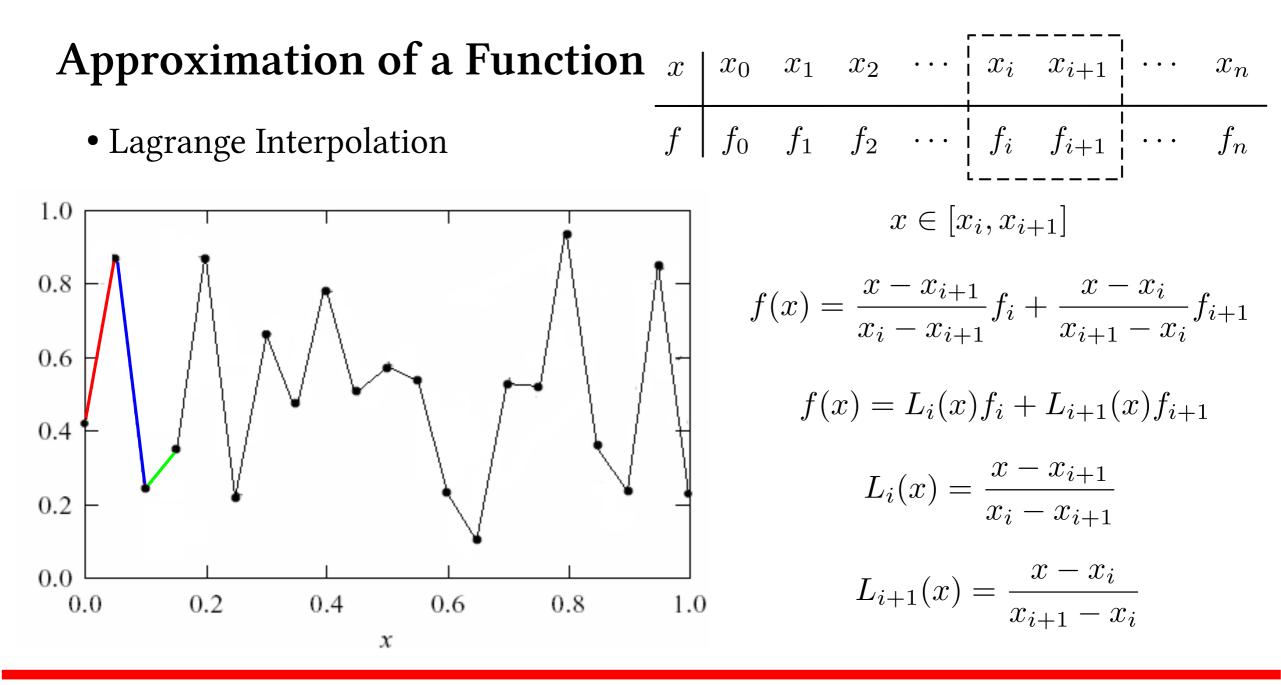
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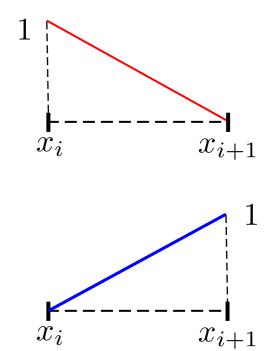
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• Lagrange Interpolation

 $r \in [r \cdot r \cdot \cdot \cdot]$

$$f(x) = \frac{x - x_{i+1}}{x_i - x_{i+1}} f_i + \frac{x - x_i}{x_{i+1} - x_i} f_{i+1} = \frac{L_i(x)}{x_i - x_{i+1}} f_i + \frac{x - x_i}{x_{i+1} - x_i} f_{i+1} = \frac{L_i(x)}{x_i - x_i} f_i + \frac{L_i(x)$$

$$L_{i}(x) = \frac{x - x_{i+1}}{x_{i} - x_{i+1}}, \quad L_{i+1}(x) = \frac{x - x_{i}}{x_{i+1} - x_{i}}$$
$$L_{i}(x_{i}) = 1, \quad L_{i}(x_{i+1}) = 0$$
$$L_{i+1}(x_{i}) = 0, \quad L_{i+1}(x_{i+1}) = 1$$



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• Lagrange Interpolation

 $\frac{\mathrm{d}}{\mathrm{d}x}\Delta f(x) = 0$ $x \in [x_i, x_{i+1}]$ Error $f(x) = \frac{x - x_{i+1}}{x_i - x_{i+1}} f_i + \frac{x - x_i}{x_{i+1} - x_i} f_{i+1} + \left| \Delta f(x) \right| \left| \frac{\mathrm{d}}{\mathrm{d}x} \Delta f(x) = \frac{\gamma}{2} [2x - (x_i + x_{i+1})] = 0$ $\Delta f(x) = \frac{\gamma}{2}(x - x_i)(x - x_{i+1})$ $x_{\max} = \frac{x_i + x_{i+1}}{2}$ $\Delta f(x_{\max}) = \frac{\gamma}{2} (x_{i+1} - x_i)^2$ $\gamma = \frac{\mathrm{d}^2 f(x)}{\mathrm{d} x^2}|_{x=a}, \quad a \in [x_i, x_{i+1}]$ $|\Delta f(x)| \leq \Delta f(x_{\max})$ $\Delta f(x = x_i) = 0, \quad \Delta f(x = x_{i+1}) = 0$

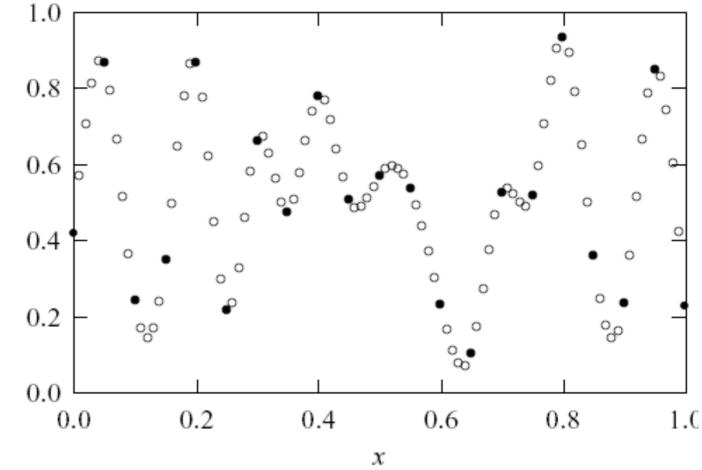
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Maximum Error:

• Lagrange Interpolation

More accurate approximation of f(x)



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• Lagrange Interpolation

$$\Delta f(x) = \frac{\gamma}{n!} (x - x_1) (x - x_2) \cdots (x - x_n)$$
$$\gamma = \frac{\mathrm{d}^n f(x)}{\mathrm{d} x^n} |_{x=a}, \quad a \in [x_1, x_n]$$

Maximum Error:

$$\frac{\mathrm{d}}{\mathrm{d}x}\Delta f(x) = 0$$

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• Spline Approximation

We want to fit the function locally and to connect each piece of the function smoothly. A spline is such a tool that interpolates the data locally through a polynomial and fits the data overall by connecting each segment of the interpolation polynomial by matching the function and its derivatives at the data points.

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 f_0

 f_2

 f_i

 \mathcal{X}

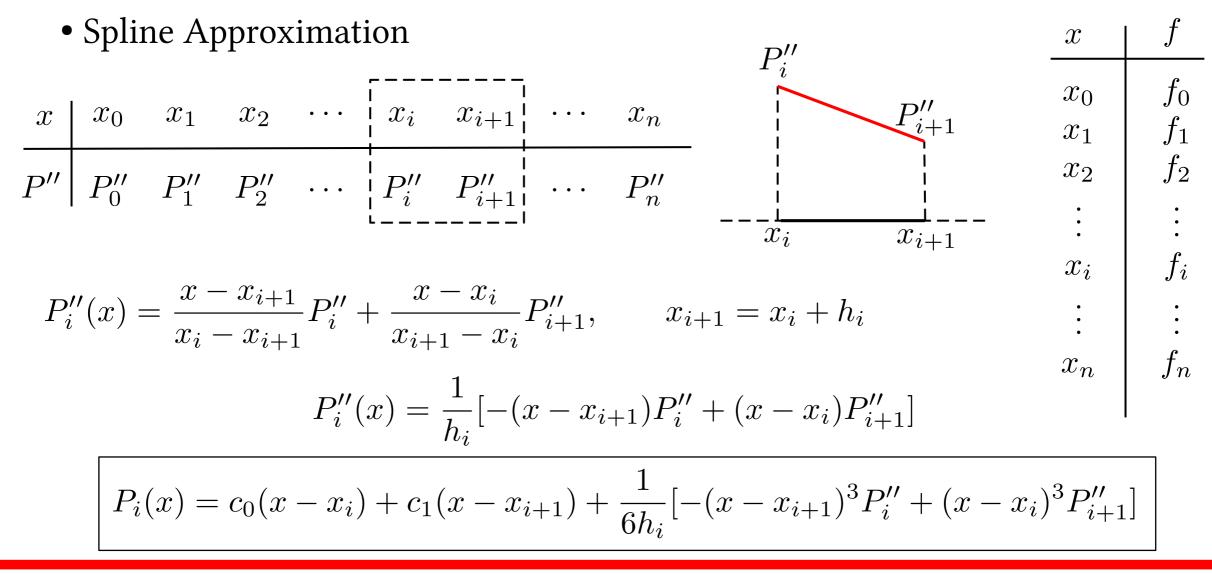
 x_0

 x_1

 x_2

•

 x_i



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• Spline Approximation

$$P_i(x) = c_0(x - x_i) + c_1(x - x_{i+1}) + \frac{1}{6h_i} \left[-(x - x_{i+1})^3 P_i'' + (x - x_i)^3 P_{i+1}'' \right]$$

$$\begin{cases} P_i(x=x_i) = f_i = -h_i c_1 + \frac{h_i^2}{6} P_i'' \\ P_i(x=x_{i+1}) = f_{i+1} = h_i c_0 + \frac{h_i^2}{6} P_{i+1}'' \end{cases} \Rightarrow \begin{cases} c_1 = -\frac{f_i}{h_i} + \frac{h_i}{6} P_i'' \\ c_0 = \frac{f_{i+1}}{h_i} - \frac{h_i}{6} P_{i+1}'' \end{cases}$$

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• Spline Approximation

$$P_{i}(x) = c_{0}(x - x_{i}) + c_{1}(x - x_{i+1}) + \frac{1}{6h_{i}} [-(x - x_{i+1})^{3} P_{i}'' + (x - x_{i})^{3} P_{i+1}'']$$

$$\begin{cases} c_{1} = -\frac{f_{i}}{h_{i}} + \frac{h_{i}}{6} P_{i}''\\ c_{0} = \frac{f_{i+1}}{h_{i}} - \frac{h_{i}}{6} P_{i+1}'' \end{cases}$$

$$P_{i}(x) = \left(\frac{f_{i+1}}{h_{i}} - \frac{h_{i}}{6}P_{i+1}''\right)(x - x_{i}) + \left(-\frac{f_{i}}{h_{i}} + \frac{h_{i}}{6}P_{i}''\right)(x - x_{i+1}) + \frac{1}{6h_{i}}\left[-(x - x_{i+1})^{3}P_{i}'' + (x - x_{i})^{3}P_{i+1}''\right]$$

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• Spline Approximation

$$\begin{bmatrix}
P_i(x) = \left(\frac{f_{i+1}}{h_i} - \frac{h_i}{6}P_{i+1}''\right)(x - x_i) + \left(-\frac{f_i}{h_i} + \frac{h_i}{6}P_i''\right)(x - x_{i+1}) \\
+ \frac{1}{6h_i}[-(x - x_{i+1})^3P_i'' + (x - x_i)^3P_{i+1}'']
\end{bmatrix} \xrightarrow{P_{i-1}} P_{i-1}' = P_i'(x_i)$$

$$i \rightarrow i - 1:$$

$$\begin{aligned} P_{i-1}(x) &= \left(\frac{f_i}{h_{i-1}} - \frac{h_{i-1}}{6}P_i''\right)(x - x_{i-1}) + \left(-\frac{f_{i-1}}{h_{i-1}} + \frac{h_{i-1}}{6}P_{i-1}''\right)(x - x_i) \\ &+ \frac{1}{6h_{i-1}}\left[-(x - x_i)^3 P_{i-1}'' + (x - x_{i-1})^3 P_i''\right] \end{aligned}$$

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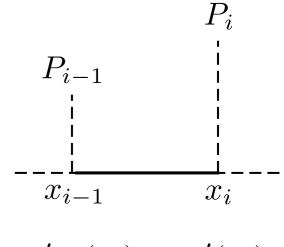
Lecture-20

 P_i

1

• Spline Approximation

$$P_i'(x) = \left(\frac{f_{i+1}}{h_i} - \frac{h_i}{6}P_{i+1}''\right) + \left(-\frac{f_i}{h_i} + \frac{h_i}{6}P_i''\right) + \frac{1}{2h_i}\left[-(x - x_{i+1})^2 P_i'' + (x - x_i)^2 P_{i+1}''\right]$$



$$P'_{i-1}(x_i) = P'_i(x_i)$$

$$P_{i-1}'(x) = \left(\frac{f_i}{h_{i-1}} - \frac{h_{i-1}}{6}P_i''\right) + \left(-\frac{f_{i-1}}{h_{i-1}} + \frac{h_{i-1}}{6}P_{i-1}''\right) + \frac{1}{2h_{i-1}}\left[-(x-x_i)^2 P_{i-1}'' + (x-x_{i-1})^2 P_i''\right]$$

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• Spline Approximation

$$P_i'(\mathbf{x}_i) = \left(\frac{f_{i+1}}{h_i} - \frac{h_i}{6}P_{i+1}''\right) + \left(-\frac{f_i}{h_i} + \frac{h_i}{6}P_i''\right) + \frac{1}{2h_i}\left[-(\mathbf{x}_i - \mathbf{x}_{i+1})^2 P_i'' + (\mathbf{x}_i - \mathbf{x}_i)^2 P_{i+1}''\right]$$

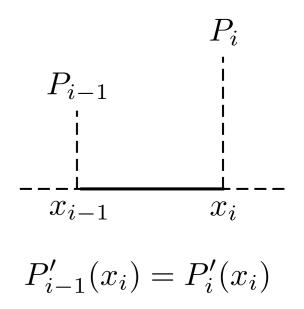
$$P_{i-1}'(x_i) = \left(\frac{f_i}{h_{i-1}} - \frac{h_{i-1}}{6}P_i''\right) + \left(-\frac{f_{i-1}}{h_{i-1}} + \frac{h_{i-1}}{6}P_{i-1}''\right) \\ + \frac{1}{2h_{i-1}}\left[-(x_i - x_i)^2 P_{i-1}'' + (x_i - x_{i-1})^2 P_i''\right]$$

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• Spline Approximation

$$P_i'(\mathbf{x}_i) = \left(\frac{f_{i+1}}{h_i} - \frac{h_i}{6}P_{i+1}''\right) + \left(-\frac{f_i}{h_i} + \frac{h_i}{6}P_i''\right) + \frac{1}{2h_i}\left[-(\mathbf{x}_i - \mathbf{x}_{i+1})^2 P_i'' + (\mathbf{x}_i - \mathbf{x}_i)^2 P_{i+1}''\right] = h_i^2$$



$$P'_{i-1}(x_i) = \left(\frac{f_i}{h_{i-1}} - \frac{h_{i-1}}{6}P''_i\right) + \left(-\frac{f_{i-1}}{h_{i-1}} + \frac{h_{i-1}}{6}P''_{i-1}\right)$$

$$+\frac{1}{2h_{i-1}}\left[-(x_i - x_i)^2 P_{i-1}'' + (x_i - x_{i-1})^2 P_i''\right] = h_{i-1}^2$$

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• Spline Approximation

$$\begin{cases} P'_{i}(x_{i}) = \left(\frac{f_{i+1}}{h_{i}} - \frac{h_{i}}{6}P''_{i+1}\right) + \left(-\frac{f_{i}}{h_{i}} + \frac{h_{i}}{6}P''_{i}\right) - \frac{h_{i}}{2}P''_{i} & \frac{-\frac{1}{x_{i-1}}}{x_{i-1}} \\ P'_{i-1}(x_{i}) = \left(\frac{f_{i}}{h_{i-1}} - \frac{h_{i-1}}{6}P''_{i}\right) + \left(-\frac{f_{i-1}}{h_{i-1}} + \frac{h_{i-1}}{6}P''_{i-1}\right) + \frac{h_{i-1}}{2}P''_{i} \\ \left(\frac{f_{i}}{h_{i-1}} - \frac{h_{i-1}}{6}P''_{i}\right) + \left(-\frac{f_{i-1}}{h_{i-1}} + \frac{h_{i-1}}{6}P''_{i-1}\right) + \frac{h_{i-1}}{2}P''_{i} = \end{cases}$$

$$\left(\frac{f_{i+1}}{h_i} - \frac{h_i}{6}P_{i+1}''\right) + \left(-\frac{f_i}{h_i} + \frac{h_i}{6}P_i''\right) - \frac{h_i}{2}P_i''$$

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Lecture-20

 P_i

 P_{i-1}

6 · | |

• Spline Approximation

$$\left(\frac{f_i}{h_{i-1}} - \frac{h_{i-1}}{6}P_i''\right) + \left(-\frac{f_{i-1}}{h_{i-1}} + \frac{h_{i-1}}{6}P_{i-1}''\right) + \frac{h_{i-1}}{2}P_i'' = \left(\frac{f_{i+1}}{h_i} - \frac{h_i}{6}P_{i+1}''\right) + \left(-\frac{f_i}{h_i} + \frac{h_i}{6}P_i''\right) - \frac{h_i}{2}P_i''$$

$$\frac{h_{i-1}}{6}P_{i-1}'' + \frac{1}{3}(h_{i-1} + h_i)P_i'' + \frac{h_i}{6}P_{i+1}'' = -\frac{f_i - f_{i-1}}{h_{i-1}} + \frac{f_{i+1} - f_i}{h_i}$$

$$\stackrel{\times 6}{\longrightarrow} h_{i-1}P_{i-1}'' + 2(h_{i-1} + h_i)P_i'' + h_iP_{i+1}'' = -6\frac{f_i - f_{i-1}}{h_{i-1}} + 6\frac{f_{i+1} - f_i}{h_i}$$

 $h_{i-1}P_{i-1}'' + 2d_iP_i'' + h_iP_{i+1}'' = b_i, \qquad d_i = h_{i-1} + h_i, \qquad b_i = -6\frac{f_i - f_{i-1}}{h_{i-1}} + 6\frac{f_{i+1} - f_i}{h_i}$

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• Spline Approximation $\begin{bmatrix} h_{i-1}P_{i-1}'' + 2d_iP_i'' + h_iP_{i+1}'' = b_i \end{bmatrix} \qquad d_i = h_{i-1} + h_i, \qquad b_i = -6\frac{f_i - f_{i-1}}{h_{i-1}} + 6\frac{f_{i+1} - f_i}{h_i}$ Suppose: $P_0'' = P_n'' = 0$ $\begin{bmatrix} d_1 & h_1 & 0 & \cdots & \cdots & 0 \\ h_1 & d_2 & h_2 & \cdots & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & \cdots & \cdots & h_{n-3} & d_{n-2} & h_{n-2} \\ 0 & \cdots & \cdots & 0 & h_{n-2} & d_{n-1} \end{bmatrix} \begin{bmatrix} P_1'' \\ P_2'' \\ \vdots \\ P_{n-2}'' \\ P_{n-1}'' \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_{n-2} \\ b_{n-1} \end{bmatrix}$

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• Spline Approximation

$$\begin{bmatrix} d_1 & h_1 & 0 & \cdots & \cdots & 0 \\ h_1 & d_2 & h_2 & \cdots & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & \cdots & \cdots & h_{n-3} & d_{n-2} & h_{n-2} \\ 0 & \cdots & \cdots & 0 & h_{n-2} & d_{n-1} \end{bmatrix} \begin{bmatrix} P_1'' \\ P_2'' \\ \vdots \\ P_{2'}'' \\ \vdots \\ P_{2'}'' \\ \vdots \\ P_{n-2}'' \\ P_{n-1}'' \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_{n-2} \\ b_{n-1} \end{bmatrix}$$

$$x \in [x_i, x_{i+1}]: P_i(x) = \left(\frac{f_{i+1}}{h_i} - \frac{h_i}{6}P_{i+1}''\right)(x - x_i) + \left(-\frac{f_i}{h_i} + \frac{h_i}{6}P_i''\right)(x - x_{i+1}) + \frac{1}{6h_i}[-(x - x_{i+1})^3P_i'' + (x - x_i)^3P_{i+1}'']$$

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